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Artificial Intelligence olume 267, February 2019, Pages 1-38

- Explanations are contrastive

 they are sought in response to particular counterfactual cases [foilsin]: people do not ask why P happened, but rather why P happened instead of Q.
- Explanation are **selected** (in a biased manner) people rarely, if ever, expect an explanation that consists of an actual and complete cause of an event. Humans are adept at selecting one or two causes (this selection is influenced by cognitive biases)





4. Explanations are social — they are presented relative to the explainer's beliefs about the explainee's beliefs.





Explanations are not just the presentation of associations and causes (causal attribution), they are contextual.

Explanation in artificial intelligence: Insights from the social sciences

Artificial Intelligence olume 267, February 2019, Pages 1-38

While an event may have many causes, often the explainee cares only about a small subset (relevant to the context), the explainer selects a subset of this subset (based on several different criteria), and explainer and explainee may interact and argue about this explanation.





Interpretability:

The degree to which an observer can understand the cause of a decision.

Or Biran & Courtenay Cotton: "Explanation and justification in machine learning: A survey," IJCAI-17 Workshop on Explainable AI (XAI), Melbourne, Australia, 20 August 2017.

The degree to which a human observer can consistently predict the model's output.

Been Kim, Rajiv Khanna & Oluwasanmi Koyejo: "Examples are not enough, learn to criticize! Criticism for interpretability." NIPS'2016









Model-Agnostic Methods

- PDP [Partial Dependence Plot], a.k.a. PD plot
- ICE [Individual Conditional Expectation]
- ALE [Accumulated Local Effects]
- LIME [Local Interpretable Model-agnostic Explanations]
- Anchors
- SHAP [Shapley Additive exPlanations]



PDP [Partial Dependence Plot]



Función de dependencia parcial

$${{\hat f}\left. {_{{x_S}}} ({x_S}) = {E_{{x_C}}}\left[{{\hat f}\left({x_S,{x_C}}
ight)}
ight] = \int {{\hat f}\left({x_S,{x_C}}
ight)} d\mathbb{P}({x_C})$$

Estimación a partir del conjunto de entrenamiento:

$${\hat f}_{x_S}(x_S) = rac{1}{n} \sum_{i=1}^n {\hat f}\left(x_S, x_C^{(i)}
ight)$$

Jerome H. Friedman: "Greedy function approximation: A gradient boosting machine." Annals of Statistics (2001): 1189-1232

Qingyuan Zhao & Trevor Hastie: "Causal interpretations of black-box models." Journal of Business & Economic Statistics, 2021



ICE [Individual Conditional Expectation]

Local method equivalent to the PDP global method, i.e. how the instance's prediction changes when a feature changes.

Variants

Centered ICE [c-ICE]

$${\hat f}_{\,cent}^{\,(i)} = {\hat f}^{\,(i)} - {f 1} {\hat f} \, (x^a, x_C^{(i)})$$

Derivative ICE [d-ICE]

$${\hat f}\left(x
ight)={\hat f}\left(x_S,x_C
ight)=g(x_S)+h(x_C), \hspace{1em} ext{with} \hspace{1em} rac{\delta {\hat f}\left(x
ight)}{\delta x_S}=g'(x_S)$$

Alex Goldstein et al.: "Peeking inside the black box: Visualizing statistical learning with plots of individual conditional expectation." Journal of Computational and Graphical Statistics 24.1 (2015): 44-65.



i.e. how features influence the prediction of a machine learning model on average

ALE [Accumulated Local Effects]

• M plots average the predictions over the conditional distribution. $\hat{f}_{x_S,M}(x_S) = E_{X_C|X_S} \left[\hat{f}(X_S, X_C) | X_S = x_s \right]$

$$=\int_{x_C} \hat{f}\left(x_S, x_C
ight) \mathbb{P}(x_C|x_S) dx_C$$

 ALE plots average the changes in the predictions and accumulate them

$${\hat f}_{x_S,ALE}(x_S) = \int_{z_{0,1}}^{x_S} E_{X_C|X_S} \left[{{\hat f}^S}(X_s,X_c) | X_S = z_S
ight] dz_S - ext{constant} \ = \int_{z_{0,1}}^{x_S} \int_{x_C} {{\hat f}^S}(z_s,x_c) \mathbb{P}(x_C|z_S) dx_C dz_S - ext{constant}$$

Daniel W. Apley: "Visualizing the effects of predictor variables in black box supervised learning models." arXiv preprint, 2016, arXiv:1612.08468

Feature Importance

IDEA: Measure the importance of a feature by calculating the increase in the model's prediction error after permuting the feature. A feature is "important" if shuffling its values increases the model error (i.e. the model relied on the feature for the prediction).

e.g. Model Reliance

Aaron Fisher, Cynthia Rudin & Francesca Dominici. "Model Class Reliance: Variable importance measures for any machine learning model class, from the 'Rashomon' perspective." arXiv, 2018. <u>https://arxiv.org/abs/1801.01489</u>









Feature Interaction

Friedman's H-statistic

Jerome H. Friedman & Bogdan E. Popescu: "Predictive learning via rule ensembles." The Annals of Applied Statistics. JSTOR, 916–54. (2008)

VIN [Variable Interaction Networks]

Giles Hooker: "Discovering additive structure in black box functions." KDD'2004, 10th ACM International Conference on Knowledge Discovery and Data Mining

Partial dependence-based feature interaction
 Brandon M. Greenwell, Bradley C. Boehmke & Andrew J. McCarthy: "A simple and effective model-based variable importance measure." arXiv preprint arXiv:1805.04755 (2018)



LIME [Local interpretable model-agnostic explanations]

Local surrogate model



Marco Tulio Ribeiro, Sameer Singh & Carlos Guestrin: "Why should I trust you?: Explaining the predictions of any classifier." KDD'2016, Proceedings of the 22nd ACM SIGKDD International Conference on Knowledge Discovery and Data Mining.

https://github.com/marcotcr/lime



Example: Wine quality



https://github.com/Milan-Chicago/Explainable-AI-Examples/blob/master/Explainable%20Notebooks/LIME/LIME.ipynb



LIME [Local interpretable model-agnostic explanations]

Warnings!

- Instability of the explanations.
 David Alvarez-Melis & Tommi S. Jaakkola: "On the robustness of interpretability methods." arXiv preprint arXiv:1806.08049 (2018)
- Hidden biases (LIME explanations can be manipulated) Dylan Slack et al.: "Fooling LIME and SHAP: Adversarial attacks on post hoc explanation methods." Proceedings of the AAAI/ACM Conference on AI, Ethics, and Society, 2020





Submodular pick for explaining models

- 1. Run the explanation model on all instances (all x's).
- 2. Compute the global importance of individual features.
- 3. Maximize the coverage function by iteratively adding
- the instance with the highest maximum coverage gain
- 4. Return a representative nonredundant explanation set.

NOTE: Greedy algorithm, since coverage maximization is NP-hard.





Anchors



Marco Tulio Ribeiro, Sameer Singh, Carlos Guestrin. "Anchors: High-Precision Model-Agnostic Explanations." AAAI Conference on Artificial Intelligence (AAAI), 2018



SHAP [SHapley Additive exPlanations]

Shapley value [@ coallitional game theory] a method for assigning payouts to players depending on their contribution to the total payout



Lloyd S. Shapley: "A value for n-person games." Contributions to the Theory of Games 2.28 (1953): 307-317



SHAP [SHapley Additive exPlanations]

Shapley value

- Linear model: $\hat{f}(x) = \beta_0 + \beta_1 x_1 + \ldots + \beta_p x_p$
- Contribution of the j-th feature to the prediction:

$$\phi_j(\hat{f}) = \beta_j x_j - E(\beta_j X_j) = \beta_j x_j - \beta_j E(X_j)$$

Sum of all the feature contributions

= predicted value - average predicted value

$$egin{aligned} &\sum_{j=1}^p \phi_j(\hat{f}\,) = \sum_{j=1}^p (eta_j x_j - E(eta_j X_j)) \ &= &(eta_0 + \sum_{j=1}^p eta_j x_j) - (eta_0 + \sum_{j=1}^p E(eta_j X_j)) \ &= &\hat{f}\,(x) - E(\hat{f}\,(X)) \end{aligned}$$



SHAP [SHapley Additive exPlanations]

Shapley value

Estimating the Shapley value through Monte Carlo sampling:

$$\hat{\phi}_j = rac{1}{M}\sum_{m=1}^M \left(\hat{f}\left(x_{+j}^m
ight) - \hat{f}\left(x_{-j}^m
ight)
ight)$$

Warnings!

- Only approximate solutions are feasible.
- Interpretation of the estimated Shapley value: the contribution of a feature value to the difference between the actual prediction and the mean prediction given the current set of feature values

Erik Štrumbelj & Igor Kononenko: "Explaining prediction models and individual predictions with feature contributions." Knowledge and Information Systems 41.3 (2014): 647-665

SHAP [SHapley Additive exPlanations]

SHAP, a method to explain individual predictions.

Scott M. Lundberg & Su-In Lee: "A unified approach to interpreting model predictions." NIPS'2017

 KernelSHAP, a kernel-based estimation approach for Shapley values inspired by local surrogate models.

$$g(z')=\phi_0+\sum_{j=1}^M\phi_j z'_j$$

SHAP feature importance:

$$I_j = \sum_{i=1}^n |\phi_j^{(i)}|$$



SHAP [SHapley Additive exPlanations]







https://github.com/slundberg/shap

SHAP [SHapley Additive exPlanations]



Example: House Pricing





SHAP pros:

- computes Shapley values (solid theoretical foundation)
- connects LIME and Shapley values (in KernelSHAP)

SHAP cons:

- slow KernelSHAP
- ignores feature dependence
- can be misinterpreted
- can be used to create intentionally misleading interpretations to hide biases (as LIME).





Example-Based Methods

explain a model by selecting instances of the dataset and not by creating summaries of features

- Counterfactual explanations
- Adversarial examples
- Prototypes
- Influential instances
- Nearest neighbors (i.e. k-NN)



Counterfactual Explanations



i.e. how an instance has to change to significantly change its prediction. (the opposite to anchors)

"If X had not occurred, Y would not have occurred"

e.g.

Sandra Wachter, Brent Mittelstadt & Chris Russell: "Counterfactual explanations without opening the black box: Automated decisions and the GDPR." Harvard Journal of Law & Technology, 2018

Susanne Dandl, Christoph Molnar, Martin Binder & Bernd Bischl: "Multi-Objective Counterfactual Explanations," Parallel Problem Solving from Nature, PPSN'2020.

Arnaud Van Looveren & Janis Klaise: "Interpretable Counterfactual Explanations Guided by Prototypes." arXiv, 2019. arXiv:1907.02584



Adversarial Examples



i.e. counterfactuals used to fool machine learning models





XAI



Neural Network Interpretation Methods

- Feature Visualization
- Pixel Attribution
 - Saliency Maps
 - Path-Attribution Methods
 - DeepLIFT
 - Deep Taylor
 - Integrated Gradients
 - XRAI
- Concepts



<image>



Feature Visualization



Lucid

https://github.com/tensorflow/lucid



Negative Neurons

What is the opposite of what a neuron is looking for? This can reveal interesting things about the representation.

Explore how neurons combine and interact. Linear

One of the main challenges to visualizing features is

regularizing the feature visualizations. Try different

techniques and fiddle with hyperparameters.

combinations, random directions in neuron space, and





Neuron Interactions

Regularizing Visualizations

interpolation.

Diversity Visualization

Neurons generally respond to multiple things --



- B.

[colab]

Semantic Dictionaries

Saving "neuron 312 fired" isn't very meaningful to humans. Combining neuron activations with feature visualization can make things much more meaningful.

Activation Grids

Activation grids can help us see how the network understood each spatial position.

Spatial Attribution

Do attribution to spatial positions in hidden layers -either from the output or other hidden layers. This is similar to traditional saliency maps.

Channel Attribution

How did different features effect the output? We can use attribution between channels in hidden layers and the output, along with feature visualization, to explore this.

Neuron Groups

Explore how groups of neurons work together to represent objects in an image. Automatically extract neuron groups and then visualize them.



Feature Visualization



Network Dissection (CVPR'2017)

http://netdissect.csail.mit.edu/



Pixel-wise segmentation



Freeze trained network weights Upsample target layer Evaluate on segmentation tasks

"By measuring the concept that best matches each unit, Net Dissection can break down the types of concepts represented in a layer"





- Gradient-only methods tell us whether a change in a pixel would change the prediction [saliency maps]
 - Vanilla Gradient
 - DeconvNet [LRP: Layer-wise Relevance Propagation]
 - Grad-CAM [Gradient-weighted Class Activation Map]
 - SmoothGrad
- Path-attribution methods compare the current image to a reference image [baseline]
 - Deep Taylor
 - DeepLIFT
 - Integrated Gradients
 - XRAI

Pixel Attribution

Saliency Maps

















Soup Bowl (vanilla)

Soup Bowl (vanilla)







Eel (vanilla)

Eel (vanilla)



Eel (Smoothgrad)



Eel (Grad-Cam)









Original



DeepLIFT [Deep Learning Important FeaTures]

ICML'2017

Reference

DeepLIFT scores





Avanti Shrikumar, Peyton Greenside, Anshul Kundaje "Learning Important Features Through Propagating Activation Differences ICML'2017, <u>https://arxiv.org/abs/1704.02685</u> <u>https://github.com/kundajelab/deeplift</u>

Pixel Attribution



DeepSHAP = DeepLIFT + Shapley values





CONTRACTOR DESISTER







Pixel Attribution

Deep Taylor









Integrated Gradients ICML'2017



https://keras.io/examples/vision/integrated gradients/

Mukund Sundararajan, Ankur Taly, Qiqi Yan "Axiomatic Attribution for Deep Networks" ICML'2017, https://arxiv.org/abs/1703.01365 https://github.com/ankurtaly/Integrated-Gradients



200

250

Pixel Attribution



XRAI: Better Attributions Through Regions ICCV'2019





Original image



Pixel-based attribution (integrated gradients)



Sum attributions and identify most important regions



Most important regions for predicted class



Concepts



TCAV [Testing with Concept Activation Vectors] ICML'2018



Figure 1. **Testing with Concept Activation Vectors:** Given a user-defined set of examples for a concept (e.g., 'striped'), and random examples (a), labeled training-data examples for the studied class (zebras) (b), and a trained network (c), TCAV can quantify the model's sensitivity to the concept for that class. CAVs are learned by training a linear classifier to distinguish between the activations produced by a concept's examples and examples in any layer (d). The CAV is the vector orthogonal to the classification boundary (v_c^l , red arrow). For the class of interest (zebras), TCAV uses the directional derivative $S_{C,k,l}(x)$ to quantify conceptual sensitivity (c).





Figure 1: *ACE* algorithm (a) A set of images from the same class is given. Each image is segmented with multiple resolutions resulting in a pool of segments all coming from the same class. (b) The activation space of one bottleneck layer of a state-of-the-art CNN classifier is used as a similarity space. After resizing each segment to the standard input size of the model, similar segments are clustered in the activation space and outliers are removed to increase coherency of clusters. (d) For each concept, its TCAV importance score is computed given its examples segments.



Concepts



CBM [Concept Bottleneck Models]

ICML'2020



Figure 1. We study concept bottleneck models that first predict an intermediate set of human-specified concepts c, then use c to predict the final output y. We illustrate the two applications we consider: knee x-ray grading and bird identification.







CW [Concept Whitening] Nature Machine Intelligence, 2020

Replace the 2nd layer (BN) with CW

Replace the 16th layer (BN) with CW

Most activated

Most activated



"When a concept whitening module is added to a CNN, the axes of the latent space are aligned with known concepts of interest."



Bibliografía



 Christoph Molnar: Interpretable Machine Learning: A Guide for Making Black Box Models Interpretable <u>https://christophm.github.io/interpretable.ml-book/</u> 2021. ISBN 0244768528
 En español (versión 2019): <u>https://fedefliguer.github.io/AAI/</u>

